

# MLFB-Ordering data

6SL3230-1YE44-0AF0



Client order no. : Order no. :

Offer no. : Remarks : Item no. :
Consignment no. :
Project :

Rated data			
3 AC			
380 480 V +10 % -20 %			
47 63 Hz			
400V IEC	480V NEC		
177.00 A	151.00 A		
154.00 A	132.00 A		
3 AC			
400V IEC	480V NEC		
	3 AC 380 480 V 47 63 Hz 400V IEC 177.00 A 154.00 A		

,		
Output		
Number of phases	3 AC	
Rated voltage	400V IEC	480V NEC
Rated power (LO)	90.00 kW	125.00 hp
Rated power (HO)	75.00 kW	75.00 hp
Rated current (LO)	178.00 A	156.00 A
Rated current (HO)	145.00 A	124.00 A
Rated current (IN)	183.00 A	
Max. output current	241.00 A	
Pulse frequency	4 kHz	
Output frequency for vector control	0 200 Hz	
Output frequency for V/f control	0 550 Hz	

General tech. specifications		
Power factor λ	0.90 0.95	
Offset factor cos φ	0.99	
Efficiency η	0.98	
Sound pressure level (1m)	72 dB	
Power loss	1.570 kW	
Filter class (integrated)	RFI suppression filter for Category C2	
EMC category (with accessories)	Category C2	
Auchieut eeuditieus		

Ambient conditions			
Standard board coating type	Class 3C3, according to IEC 60721-3-3: 2002		
Cooling	Air cooling using an integrated fan		
Cooling air requirement	0.153 m³/s (5.403 ft³/s)		
Installation altitude	1000 m (3280.84 ft)		
Ambient temperature			
Operation	-20 45 °C (-4 113 °F)		
Transport	-40 70 °C (-40 158 °F)		
Storage	-25 55 °C (-13 131 °F)		

#### **Relative humidity**

	95 % At 40 °C (104 °F), condensation
Max. operation	and icing not permissible

#### Overload capability

Low Overload (LO)

110% base load current IL for 60 s in a 300 s cycle time

High Overload (HO)

150% x base load current IH for 60 s within a 600 s cycle time



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Mechanical	data	Closed-loop cont	rol techniques
Degree of protection	IP20 / UL open type		ioi teemilyaes
Size	FSF	V/f linear / square-law / parameteriza	<b>ble</b> Yes
Net weight	68 kg (149.91 lb)	V/f with flux current control (FCC)	Yes
	-	V/f ECO linear / square-law	Yes
Width	305 mm (12.01 in)	Sensorless vector control	Yes
Height	709 mm (27.91 in)	Vector control, with sensor	No
Depth	369 mm (14.53 in)	Encoderless torque control	Yes
Inputs / out	puts	Encoderiess torque control	res
Standard digital inputs		Torque control, with encoder	No
Number	6	Communi	
Switching level: 0→1	11 V	Communication	
Switching level: 1→0	5 V		PROFINET, EtherNet/IP
Max. inrush current	15 mA	Connections	
Fail-safe digital inputs	13 111/1	Signal cable	
Number	1	( ONGLICTOR CROSS-SOCTION	0.15 1.50 mm² (AWG 24 AWG 16)
Digital outputs		Line side	
Number as relay changeover contact	2	Version	M10 screw
Output (resistive load)	DC 30 V, 5.0 A		35.00 120.00 mm² (AWG 1 AWG 4/0)
Number as transistor	0	Motor end	
Analog / digital inputs		Version	M10 screw
Number	2 (Differential input)		35.00 120.00 mm² (AWG 1 AWG 4/0)
Resolution	10 bit	DC link (for braking resistor)	· · · · · · · · · · · · · · · · · · ·
Switching threshold as digital in	out	<u> </u>	M10 screw
0→1	4 V	Max. motor cable length	
1→0	1.6 V	-	150 m (492.13 ft)
Analog outputs			

### PTC/ KTY interface

Number

1 motor temperature sensor input, sensors that can be connected: PTC, KTY and Thermo-Click, accuracy  $\pm 5~^{\circ}\text{C}$ 

1 (Non-isolated output)



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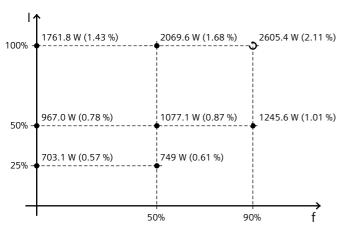
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Figure similar

### Converter losses to EN 50598-2\*

Efficiency class	IE2
Comparison with the reference converter (90% / 100%)	-51.40 %



 $The \ percentage \ values \ show \ the \ losses \ in \ relation \ to \ the \ rated \ apparent \ power \ of \ the \ converter.$ 

The diagram shows the losses for the points (as per standard EN 50598) of the relative torque generating current (I) over the relative motor stator frequency(f). The values are valid for the basic version of the converter without options/components.

# Standards

Compliance with standards UL, cUL, CE, C-

UL, cUL, CE, C-Tick (RCM), EAC, KCC, SEMI F47, REACH

**CE** marking

EMC Directive 2004/108/EC, Low-Voltage Directive 2006/95/EC

<sup>\*</sup>converted values