Product data sheet Characteristics

ATV32HU75N4

variable speed drive ATV32 - 7.5 kw - 400 V - 3 phase - with heat sink

Product availability: Stock - Normally stocked in distribution facility



Price*: 1590.00 USD



Main

Man		يّ
Range of product	Altivar 32	
Product or component type	Variable speed drive	a 24
Product destination	Synchronous motors Asynchronous motors	a bility of the
Product specific application	Complex machines	
Function available	-	
Assembly style	With heat sink	mindeline interimental
Component name	ATV32	
EMC filter	Class C2 EMC filter integrated	
Phase	3 phases	1
[Us] rated supply voltage	380500 V - 1510 %	
Supply voltage limits	323550 V	======================================
Supply frequency	5060 Hz - 55 %	
Network frequency	47.563 Hz	
Motor power kW	7.5 kW 380480 V	, <u> </u>
Motor power hp	10 hp 380480 V	

Complementary

Line current 18.7 A 500 V 3 phases 7.5 kW 10 hp 26.5 A 380 V 3 phases 7.5 kW 10 hp Apparent power 22.9 kVA 500 V 3 phases 7.5 kW 15 hp Prospective line lsc <= 22 kA 3 phases	,
	1000
Prospective line lsc <= 22 kA 3 phases	
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Nominal output current 17 A 4 kHz 500 V 7.5 kW 10 hp	
Maximum transient current 25.5 A 60 s 7.5 kW 10 hp	
Output frequency 0.00050.599 kHz	
Nominal switching frequency 4 kHz	

Switching frequency	216 kHz adjustable
Speed range	1100 asynchronous motor in open-loop mode
Speed accuracy	+/- 10 % of nominal slip 0.2 Tn to Tn
Torque accuracy	+/- 15 %
Transient overtorque	170200 %
Braking torque	<= 170 % with braking resistor
Asynchronous motor control profile	Voltage/Frequency ratio, 5 points Flux vector control without sensor - Energy Saving, NoLoad law Voltage/Frequency ratio, 2 points Voltage/Frequency ratio - Energy Saving, quadratic U/f Flux vector control without sensor, standard
Synchronous motor control profile	Vector control without sensor
Regulation loop	Adjustable PID regulator
Motor slip compensation	Adjustable 0300 % Automatic whatever the load Not available in voltage/frequency ratio (2 or 5 points)
Local signalling	1 LED green CANopen run 1 LED red CANopen error 1 LED red drive fault 1 LED red drive voltage
Output voltage	<= power supply voltage
Noise level	43 dB 86/188/EEC
Insulation	Electrical between power and control
Electrical connection	Screw terminal 0.51.5 mm² AWG 18AWG 14 control Removable screw terminals 2.516 mm² AWG 12AWG 6 motor/braking resistor Screw terminal 616 mm² AWG 8AWG 6 power supply
Tightening torque	4.42 lbf.in (0.5 N.m) 4.4 lb/ft control 10.62 lbf.in (1.2 N.m) 10.6 lb/ft motor/braking resistor 10.62 lbf.in (1.2 N.m) 10.6 lb/ft power supply
Supply	Internal supply for reference potentiometer (1 to 10 kOhm) 10.5 V DC +/- $5\% \le 10$ mA overload and short-circuit protection
Analogue input number	3
Analogue input type	Voltage Al1 010 V DC 30000 Ohm 10 bits
gao mpat typo	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits
Sampling duration	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10
	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits 2 ms Al1, Al2, Al3 analog
Sampling duration	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits 2 ms Al1, Al2, Al3 analog 2 ms AO1 analog 8 ms +/- 0.7 ms Ll1Ll6 logic 2 ms R1A, R1B, R1C relay
Sampling duration Response time	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits 2 ms Al1, Al2, Al3 analog 2 ms AO1 analog 8 ms +/- 0.7 ms Ll1Ll6 logic 2 ms R1A, R1B, R1C relay 2 ms R2A, R2C relay +/- 0.2 % Al1, Al2, Al3 for a temperature of -1060 °C +/- 0.5 % Al1, Al2, Al3 for a temperature of 25 °C +/- 1 % AO1 for a temperature of 25 °C
Sampling duration Response time Accuracy	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits 2 ms Al1, Al2, Al3 analog 2 ms AO1 analog 8 ms +/- 0.7 ms Ll1Ll6 logic 2 ms R1A, R1B, R1C relay 2 ms R2A, R2C relay +/- 0.2 % Al1, Al2, Al3 for a temperature of -1060 °C +/- 0.5 % Al1, Al2, Al3 for a temperature of 25 °C +/- 1 % AO1 for a temperature of 25 °C +/- 2 % AO1 for a temperature of -1060 °C +/- 0.20.5 % of maximum value Al1, Al2, Al3
Sampling duration Response time Accuracy Linearity error	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits 2 ms Al1, Al2, Al3 analog 2 ms AO1 analog 8 ms +/- 0.7 ms Ll1Ll6 logic 2 ms R1A, R1B, R1C relay 2 ms R2A, R2C relay +/- 0.2 % Al1, Al2, Al3 for a temperature of -1060 °C +/- 0.5 % Al1, Al2, Al3 for a temperature of 25 °C +/- 1 % AO1 for a temperature of 25 °C +/- 2 % AO1 for a temperature of -1060 °C +/- 0.20.5 % of maximum value Al1, Al2, Al3 +/- 0.3 % AO1
Sampling duration Response time Accuracy Linearity error Analogue output number	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits 2 ms Al1, Al2, Al3 analog 2 ms AO1 analog 8 ms +/- 0.7 ms Ll1Ll6 logic 2 ms R1A, R1B, R1C relay 2 ms R2A, R2C relay +/- 0.2 % Al1, Al2, Al3 for a temperature of -1060 °C +/- 0.5 % Al1, Al2, Al3 for a temperature of 25 °C +/- 1 % AO1 for a temperature of 25 °C +/- 2 % AO1 for a temperature of -1060 °C +/- 0.20.5 % of maximum value Al1, Al2, Al3 +/- 0.3 % AO1 1 Software-configurable current AO1 020 mA 800 Ohm 10 bits
Sampling duration Response time Accuracy Linearity error Analogue output number Analogue output type	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits 2 ms Al1, Al2, Al3 analog 2 ms AO1 analog 8 ms +/- 0.7 ms Ll1Ll6 logic 2 ms R1A, R1B, R1C relay 2 ms R2A, R2C relay +/- 0.2 % Al1, Al2, Al3 for a temperature of -1060 °C +/- 0.5 % Al1, Al2, Al3 for a temperature of 25 °C +/- 1 % AO1 for a temperature of 25 °C +/- 2 % AO1 for a temperature of -1060 °C +/- 0.20.5 % of maximum value Al1, Al2, Al3 +/- 0.3 % AO1 Software-configurable current AO1 020 mA 800 Ohm 10 bits Software-configurable voltage AO1 010 V 470 Ohm 10 bits
Sampling duration Response time Accuracy Linearity error Analogue output number Analogue output type Discrete output number	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits 2 ms Al1, Al2, Al3 analog 2 ms AO1 analog 8 ms +/- 0.7 ms Ll1Ll6 logic 2 ms R1A, R1B, R1C relay 2 ms R2A, R2C relay +/- 0.2 % Al1, Al2, Al3 for a temperature of -1060 °C +/- 0.5 % Al1, Al2, Al3 for a temperature of 25 °C +/- 1 % AO1 for a temperature of 25 °C +/- 2 % AO1 for a temperature of -1060 °C +/- 0.20.5 % of maximum value Al1, Al2, Al3 +/- 0.3 % AO1 Software-configurable current AO1 020 mA 800 Ohm 10 bits Software-configurable voltage AO1 010 V 470 Ohm 10 bits 3 Configurable relay logic R1A, R1B, R1C NO/NC 100000 cycles Configurable relay logic R2A, R2B NO 100000 cycles
Sampling duration Response time Accuracy Linearity error Analogue output number Analogue output type Discrete output number Discrete output type	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits 2 ms Al1, Al2, Al3 analog 2 ms AO1 analog 8 ms +/- 0.7 ms Ll1Ll6 logic 2 ms R1A, R1B, R1C relay 2 ms R2A, R2C relay +/- 0.2 % Al1, Al2, Al3 for a temperature of -1060 °C +/- 0.5 % Al1, Al2, Al3 for a temperature of 25 °C +/- 1 % AO1 for a temperature of 25 °C +/- 2 % AO1 for a temperature of -1060 °C +/- 0.20.5 % of maximum value Al1, Al2, Al3 +/- 0.3 % AO1 1 Software-configurable current AO1 020 mA 800 Ohm 10 bits Software-configurable voltage AO1 010 V 470 Ohm 10 bits 3 Configurable relay logic R1A, R1B, R1C NO/NC 100000 cycles Configurable relay logic R2A, R2B NO 100000 cycles Logic LO
Sampling duration Response time Accuracy Linearity error Analogue output number Analogue output type Discrete output number Discrete output number Minimum switching current	Bipolar differential voltage Al2 +/- 10 V DC 30000 Ohm 10 bits Current Al3 020 mA (or 4-20 mA, x-20 mA, 20-x mA or other patterns by configuration) 250 Ohm 10 bits 2 ms Al1, Al2, Al3 analog 2 ms AO1 analog 8 ms +/- 0.7 ms Ll1Ll6 logic 2 ms R1A, R1B, R1C relay 2 ms R2A, R2C relay +/- 0.2 % Al1, Al2, Al3 for a temperature of -1060 °C +/- 0.5 % Al1, Al2, Al3 for a temperature of 25 °C +/- 1 % AO1 for a temperature of 25 °C +/- 2 % AO1 for a temperature of -1060 °C +/- 0.20.5 % of maximum value Al1, Al2, Al3 +/- 0.3 % AO1 Software-configurable current AO1 020 mA 800 Ohm 10 bits Software-configurable voltage AO1 010 V 470 Ohm 10 bits 3 Configurable relay logic R1A, R1B, R1C NO/NC 100000 cycles Configurable relay logic R2A, R2B NO 100000 cycles Logic LO 5 mA 24 V DC configurable relay logic 3 A 250 V AC resistive (cos phi = 1 R1 4 A 30 V DC resistive (cos phi = 1 R1 2 A 250 V AC resistive (cos phi = 0.4 R1, R2 2 A 30 V DC inductive (cos phi = 0.4 R1, R2 2 A 350 V AC resistive (cos phi = 0.4 R1, R2 5 A 250 V AC resistive (cos phi = 1 R2

	B
	Programmable as pulse input 20 kpps LI5 2430 V DC level 1 PLC Switch-configurable PTC probe LI6 2430 V DC Safe torque off STO 2430 V DC 1500 Ohm
Discrete input logic	Negative logic (sink) LI1LI6 > 19 V < 13 V Positive logic (source) LI1LI6 < 5 V > 11 V
Acceleration and deceleration ramps	Deceleration ramp adaptation U Linear Deceleration ramp automatic stop DC injection CUS Ramp switching S
Braking to standstill	By DC injection
Protection type	Input phase breaks drive Overcurrent between output phases and earth drive Overheating protection drive Short-circuit between motor phases drive Thermal protection drive
Communication port protocol	CANopen Modbus
Connector type	1 RJ45 Modbus/CANopen on front face
Physical interface	2-wire RS 485 Modbus
Transmission frame	RTU Modbus
Type of polarization	No impedance Modbus
Number of addresses	1247 Modbus 1127 CANopen
Method of access	Slave CANopen
Electromagnetic compatibility	Conducted radio-frequency immunity test level 3 IEC 61000-4-6 Voltage dips and interruptions immunity test IEC 61000-4-11 1.2/50 µs - 8/20 µs surge immunity test level 3 IEC 61000-4-5 Electrical fast transient/burst immunity test level 4 IEC 61000-4-4 Electrostatic discharge immunity test level 3 IEC 61000-4-2 Radiated radio-frequency electromagnetic field immunity test level 3 IEC 61000-4-3
Width	5.91 in (150 mm)
Height	12.13 in (308 mm)
Depth	9.13 in (232 mm)
Product weight	16.53 lb(US) (7.5 kg)
Option card	Communication card CANopen daisy chain Communication card CANopen open style Communication card DeviceNet Communication card Ethernet/IP Communication card Profibus DP V1
Functionality	Mid
Specific application	Other applications

Environment

Standards	EN 61800-3 environments 2 category C2 EN/IEC 61800-3 EN 55011 class A group 1 EN/IEC 61800-5-1 EN 61800-3 environments 1 category C2
Product certifications	CSA GOST NOM 117 UL C-Tick
Marking	CE
Pollution degree	2 EN/IEC 61800-5-1
IP degree of protection	IP20 EN/IEC 61800-5-1
Vibration resistance	1 gn 13200 Hz EN/IEC 60068-2-6 1.5 mm peak to peak 313 Hz EN/IEC 60068-2-6
Shock resistance	15 gn 11 ms EN/IEC 60068-2-27
Relative humidity	595 % without condensation IEC 60068-2-3

5	05 %	without	drinning water	IFC 60068-2-3	
ລ	90 %	WHILIOHII	annonna warer	1FL DUUDA-7-3	

Ambient air temperature for operation	14122 °F (-1050 °C) without derating 122140 °F (5060 °C) with derating factor
Ambient air temperature for storage	-13158 °F (-2570 °C)
Operating altitude	<= 3280.84 ft (1000 m) without derating 3280.849842.52 ft (10003000 m) with current derating 1 % per 100 m
Operating position	Vertical +/- 10 degree

Ordering and shipping details

Category	22153 - ATV312 / ATV32 (10 THRU 30 HP)
Discount Schedule	CP4B
GTIN	00785901632627
Nbr. of units in pkg.	1
Package weight(Lbs)	12.28000000000001
Returnability	N
Country of origin	ID

Offer Sustainability

Sustainable offer status	Green Premium product	
RoHS (date code: YYWW)	Compliant - since 1012 - Schneider Electric declaration of conformity	
	Schneider Electric declaration of conformity	
REACh	Reference not containing SVHC above the threshold	
	Reference not containing SVHC above the threshold	
Product environmental profile	Available	
	Product Environmental Profile	
Product end of life instructions	Available	

Contractual warranty

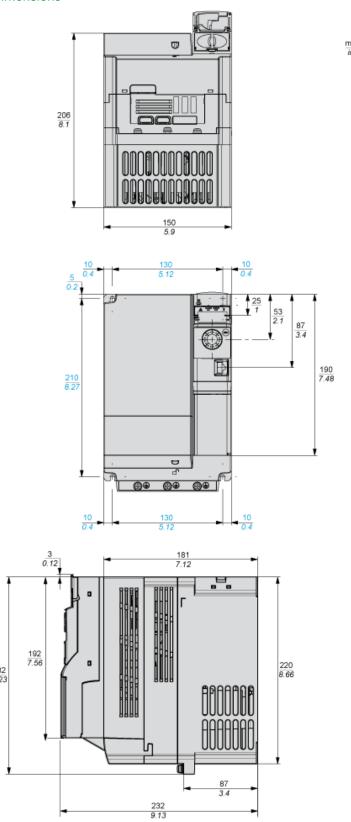
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Product data sheet Dimensions Drawings

ATV32HU75N4

Size C

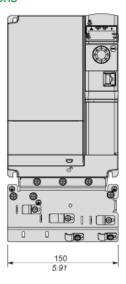
Dimensions

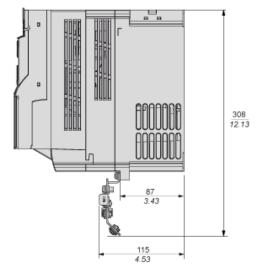


ATV32HU75N4

Size C - with EMC plate

Dimensions

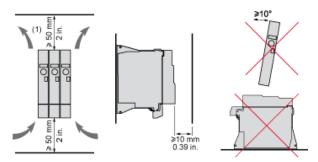




Product data sheet Mounting and Clearance

ATV32HU75N4

Mounting and Clearance



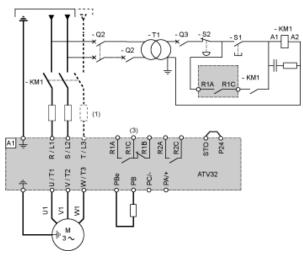
(1) Minimum value corresponding to thermal constraints.

ATV32HU75N4

Connection Diagrams

Single or Three-phase Power Supply - Diagram with Line Contactor

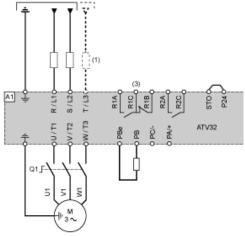
Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



- Line choke (if used)
- (1) (3) Fault relay contacts, for remote signaling of drive status

Single or Three-phase Power Supply - Diagram with Switch Disconnect

Connection diagrams conforming to standards EN 954-1 category 1 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.



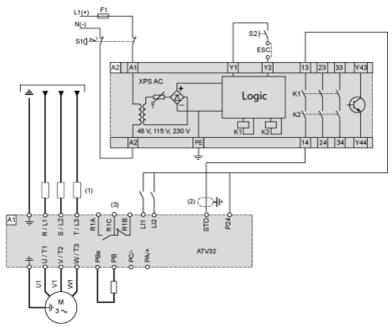
- Line choke (if used) (1)
- (3) Fault relay contacts, for remote signaling of drive status

Diagram with Preventa Safety Module (Safe Torque Off Function)

Connection diagrams conforming to standards EN 954-1 category 3 and IEC/EN 61508 capacity SIL2, stopping category 0 in accordance with standard IEC/EN 60204-1.

When the emergency stop is activated, the drive power supply is cut immediately and the motor stops in freewheel, according to category 0 of standard IEC/EN 60204-1.

A contact on the Preventa XPS AC module must be inserted in the brake control circuit to engage it safely when the STO (Safe Torque Off) safety function is activated.



- (1) Line choke (if used)
- (2) It is essential to connect the shielding to the ground.
- (3) Fault relay contacts, for remote signaling of drive status

The STO safety function integrated into the product can be used to implement an "EMERGENCY STOP" (IEC 60204-1) for category 0 stops.

With an additional, approved EMERGENCY STOP module, it is also possible to implement category 1 stops.

STO function

The STO safety function is triggered via 2 redundant inputs. The circuits of the two inputs must be separate so that there are always two channels. The switching process must be simultaneous for both inputs (offset < 1 s).

The power stage is disabled and an error message is generated. The motor can no longer generate torque and coasts down without braking. A restart is possible after resetting the error message with a "Fault Reset".

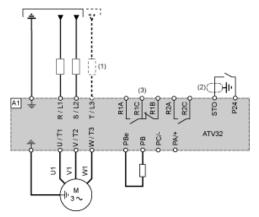
The power stage is disabled and an error message is generated if only one of the two inputs is switched off or if the time offset is too great. This error message can only be reset by switching off the product.

Diagram without Preventa Safety Module

Connection diagrams conforming to standards EN 954-1 category 2 and IEC/EN 61508 capacity SIL1, stopping category 0 in accordance with standard IEC/EN 60204-1.

The connection diagram below is suitable for use with machines with a short freewheel stop time (machines with low inertia or high resistive torque).

When the emergency stop is activated, the drive power supply is cut immediately and the motor stops in freewheel, according to category 0 of standard IEC/EN 60204-1.

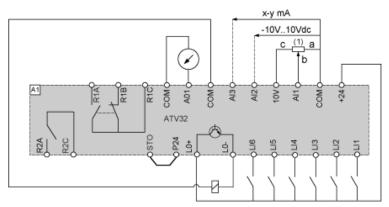


- (1) Line choke (if used)
- (2) It is essential to connect the shielding to the ground.
- (3) Fault relay contacts, for remote signaling of drive status

The STO safety function integrated into the product can be used to implement an "EMERGENCY STOP" (IEC 60204-1) for category 0 stops.

ATV32HU75N4

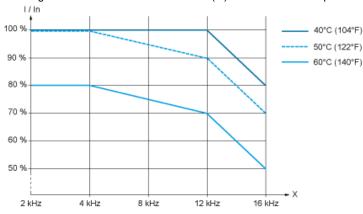
Control Connection Diagram in Source Mode



(1) Reference potentiometer SZ1RV1202 (2.2 k Ω) or similar (10 k Ω maximum)

Derating Curves

Derating curve for the nominal drive current (In) as a function of temperature and switching frequency.



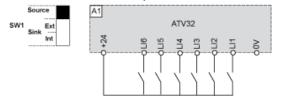
X Switching frequency

Above 4 kHz, the drive will reduce the switching frequency automatically in the event of an excessive temperature rise.

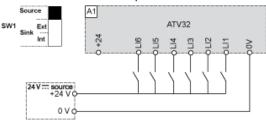
Technical Description

Sink / Source Switch Configuration (SW1)

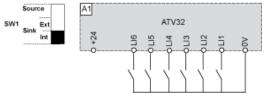
The logic input switch (SW1) is used to adapt the operation of the logic inputs to the technology of the programmable controller outputs. Switch SW1 set to "Source" position



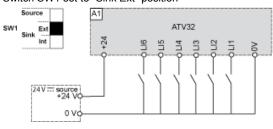
Switch SW1 set to "Source" position and use of an external power supply for the LIs



Switch SW1 set to "Sink Int" position



Switch SW1 set to "Sink Ext" position



Product Life Status END OF COMMERCIALIZATION